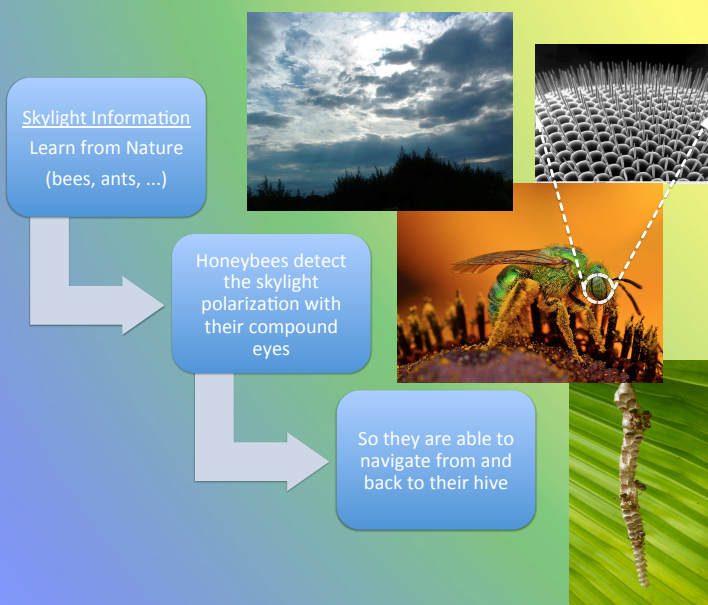


GPS-Independent Navigation:



Honeybee Navigation:

- ❖ Honeybees memorize landmarks and gather information about the skylight polarization to navigate from and to their hive.
- ❖ The skylight polarization changes over the day and is visible even if the sun is hidden behind clouds.
- ❖ We can adapt this ability of the honeybee by using a

Bio-inspired polarized
light-based MEMS
navigation device

and applying the Rayleigh sky model.

MEMS Device Concept:

1. The MEMS-based sensor array is based on abstractions of biological functions such as the skylight navigation of honeybees (*Apis mellifera*), which are able to see the skylight polarization. This ability is also used to detect humidity richer air masses near ground. We also investigate and transferred how elephants (*Loxodonta africana*) detect water.
2. To actually build our navigation device, we use light beam reactive MEMS; these can sense skylight polarization based on the Rayleigh sky model. The approach to detect water within our atmosphere with MEMS also builds up on the polarization effect and furthermore on the ability to detect underground rivers via characteristics of the emitted infrasound spectrum (as used by elephants when finding water).

Bioinspired Water Detection with MEMS:

